



# A Benchmark for Deep Learning Reconstruction Methods for Low-Dose Computed Tomography

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# Motivation

- Learned methods in imaging boost reconstruction quality
- Often only limited amount of paired data available

## Contributions

- 1 Compare different classical and deep learning approaches for CT reconstruction in low-dose scenarios
- 2 Investigate the influence of the number of training and validation samples on the performance of learned models
- 3 Explore ways to use the Deep Image Prior (DIP) for CT reconstruction



## Reduction Strategies

- 1.5% of all cancers in the U.S. might relate to current CT usage [4]
- Low-dose CT can lead to challenges for the reconstruction models
- We include two common reduction strategies in our study:
  - 1 **Sparse angle**: undersampled  
→ Synthetic Ellipses Dataset
  - 2 **Low photon count**: Poisson noise  
→ LoDoPaB-CT Dataset [8]
- Both datasets are easily accessible through our python library  $DIV_{\alpha}^1$

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<sup>1</sup>[pypi.org/project/dival](https://pypi.org/project/dival)

## Synthetic Ellipses Dataset

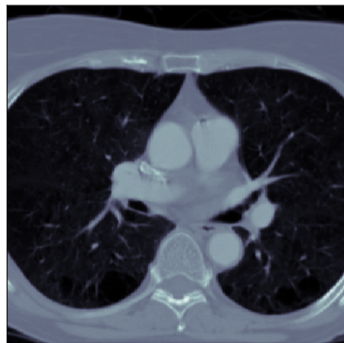
- Random ellipse phantoms
- Around 40 000 images in total
- Sparse angle setup
- Undersampled & Gaussian noise





## LoDoPaB-CT Dataset

- Thoracic CT scans from the LIDC/IDRI database [3]
- Over 800 patients and 40 000 scan slices
- Low photon count setting
- Poisson noise





## Definition DIP [7]

For fixed input  $z$  and neural network  $\varphi$  with parameters  $\theta$  solve

$$\hat{\theta} = \arg \min_{\theta \in \Theta} \|A\varphi(\theta, z) - y^\delta\|^2, \quad \hat{x} = \varphi(\hat{\theta}, z)$$

- No ground truth and training data needed
- Optimize using gradient descent with early stopping
- Regularization is a combination of early stopping and the architecture



## Our Approaches for CT

### 1 Deep Image Prior + Regularization

- Add an additional regularization term  $\mathcal{R}$  with weighting factor  $\alpha \in \mathbb{R}^+$

$$\hat{\theta} = \arg \min_{\theta \in \Theta} \|A\varphi(\theta, z) - y^\delta\|^2 + \alpha \mathcal{R}(\varphi(\theta, z))$$

- Choose Total Variation (TV)  $\mathcal{R}(\cdot) = \|\nabla \cdot\|_1$  for sparse gradients [9]

### 2 Start with an initial reconstruction

- Choose  $z$  as output of another reconstruction algorithm
- Can lead to better reconstructions and fewer optimization steps
- DIP can adapt the initial algorithm to a new setting without retraining





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## Compared Methods

### Methods without training

- Filtered Backprojection (FBP)
- Total Variation (TV)
- Deep Image Prior (DIP) + TV

### Fully-learned inversion

- iRadonMap [5]

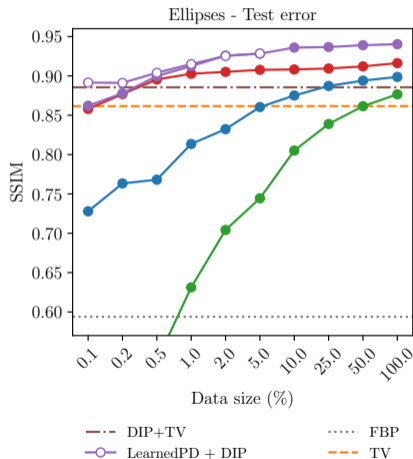
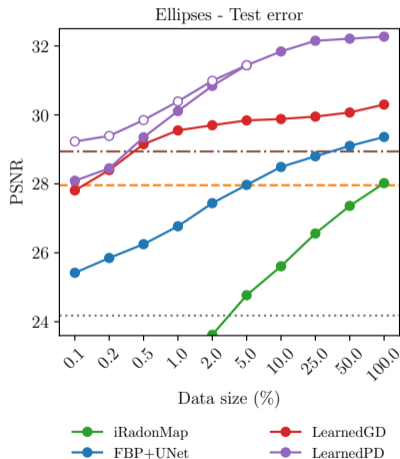
### Learned iterative schemes

- Learned Gradient Descent (LearnedGD) [2]
- Learned Primal-Dual (LearnedPD) [1]

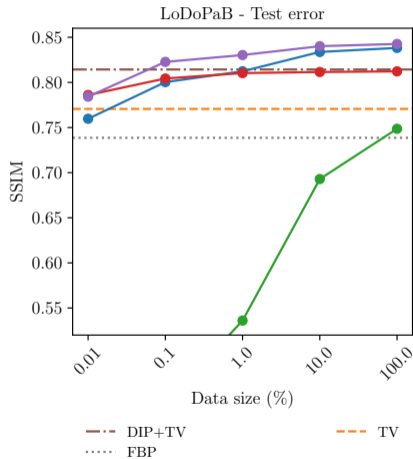
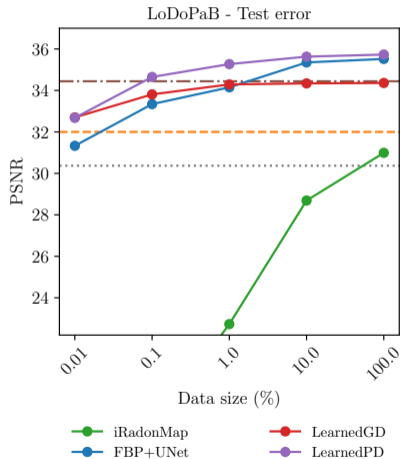
### Post-processing

- FBP + U-Net [6]
- LearnedPD + DIP

# Ellipses Dataset



# LoDoPaB-CT Dataset





## Thanks for your Attention!

Follow the link below or scan the QR code for additional information



[dival.math.uni-bremen.de/isbi2020\\_ct\\_dip\\_dl](https://dival.math.uni-bremen.de/isbi2020_ct_dip_dl)



## Bibliography I

- [1] J. Adler et al. “Learned Primal-Dual Reconstruction”. In: *IEEE Transactions on Medical Imaging* 37.6 (June 2018), pp. 1322–1332. DOI: 10.1109/TMI.2018.2799231.
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- [6] K. H. Jin et al. “Deep Convolutional Neural Network for Inverse Problems in Imaging”. In: *IEEE Transactions on Image Processing* 26.9 (Sept. 2017), pp. 4509–4522. ISSN: 1057-7149. DOI: 10.1109/TIP.2017.2713099.



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